



# **Application Note**

**Monitoring strategy – Condition Monitoring of Jet Fans** 





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#### Scope

The machine monitoring strategy described in this document is applicable for all types of direct-drive jet fans with rolling element bearings. They are typically powered by an integrated fully reversible variable speed motor. The most common application for jet fans are for ventilation and smoke control in case of a fire in tunnels for road, rail and metros.

# Machine Operation and Maintenance Requirements

The amount and type of maintenance required for jet fans is highly dependent on the environmental conditions such as temperature, amount of pulsation pressure, dust, etc. There is consequently a wide range of different failure modes that can occur. Typical faults include unbalance (due to blade deposits), misalignment, bent shaft and damaged bearings and damaged motor.

If unchecked, these potential failure modes can consequently result in reducing operating efficiency and provoke excessive loading on components leading to



premature bearing failure, stator/rotor rub, component damage or even a catastrophic failure. A catastrophic failure of a jet fan in certain cases could require tunnel closure.

### Monitoring Strategy

A condition monitoring strategy is intended to detect most developing faults at an early enough stage such that maintenance can be cost-effectively planned ahead of time without stopping the machine.

The monitoring strategy for this particular machine is focused on the Brüel & Kjær Vibro VDAU-6000 system (all monitoring and analysis techniques are built in) and described in the following pages.

The VDAU-6000 data can be exported to the control system via OPC, Modbus and Brüel & Kjær Vibro's proprietary database protocol. The data can be imported to existing software platforms via http request.



### Monitoring configuration and techniques

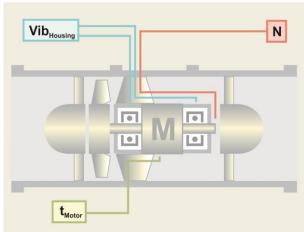


Figure 1. Monitoring inputs .

Symbol	Signal		
Absolute Vibration Monitoring Sensors			
Vib <sub>Housing</sub>	2x Bearing housing radial vibration		
	(accelerometer)		
Relative Vibration Monitoring Sensors			
N	Shaft speed, phase referencing,		
	tracking		
Process Values (Imported from DCS or by installed			
sensors)			
t <sub>Motor</sub>	Motor temperature		

Table 1. Input signal symbols.





#### Monitoring configuration and techniques (cont.)

Sensor Location (type)	Measurements	Plots	Faults that can be detected and diagnosed
Shaft (Tacho)	Speed, phase	Trend vs. time	Phase, tracking and triggering used in other measurements
Bearing housing (Absolute radial vibration)	Overall (ISO:1Hz/10Hz - 1kHz)     Autospectrum (FFT)     Cepstrum     Envelope spectrum     Blade passing frequency     Bearing fault frequencies	Trend vs. time/speed  Spectrum (FFT, Cepstrum, Envelope)  Waterfall (FFT, Cepstrum, Envelope)  Time waveform	Unbalance, misalignment, bent shaft, resonances, bearing faults, blade faults, motor faults, structural faults
Motor (Process)	DC (motor temp.)	Trend vs. time/speed	Motor damage due to excess heat, lack of lubrication, overload, wear

Table 2. Monitoring techniques.

Sensor	Analysis techniques	Purpose	Faults that can be detected
Location			and diagnosed
(type)			
Bearing	Event analysis (complete data download during	Root cause	Unbalance, misalignment,
housing	an event or by request)	analysis	bent shaft, resonances, bearing faults, blade faults, motor faults, structural faults
(Absolute	Automatic machine diagnostics (two or more	Automatic	
radial	descriptors set up to identify specific faults)	diagnostics	
vibration)	, , , , , , , , , , , , , , , , , , , ,		

Table 3. Analysis techniques.

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